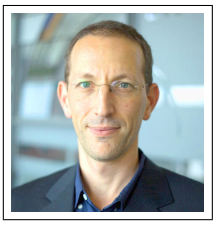
Shai Revzen

+1-(215)-906-2556
shrevzen@umich.edu
http://www.birds.eecs.umich.edu



Education

2020 (exp. 2023) **J.D.**, *Wayne State Univ.*, Detroit.
Law

2003 Dec 2009 **Ph.D.**, *Univ. California*, Berkeley.
Integrative Biology

1994 Jun 2002 **M.Sc.**, *Hebrew Univ.*, Jerusalem.
Computer Science (Optimization)

1989 May 1993 **B.Sc.**, *Hebrew Univ.*, Jerusalem, *Magna cum laude*.
Degree from honours program; Majors Computer Science, Math (extended); Minor Physics

Doctoral thesis

title Neuromechanical Control Architectures in Arthropod Locomotion
supervisor Robert J. Full

Master thesis

title Paging on Access Graphs of Minimal Degree 3
supervisor Nati Linial

Work Experience

Academia

19–now **Associate Professor**, *U. Michigan (Ecology and Evolutionary Biology)*, Ann Arbor.
Research, student supervision; biomechanics and mathematical biology

19–now **Associate Professor**, *U. Michigan (Electrical Engineering and Computer Science)*, Ann Arbor.
Research, student supervision; robotics and control theory

12–19 **Assistant Professor**, *U. Michigan (Ecology and Evolutionary Biology)*, Ann Arbor.
Research, student supervision; biomechanics and mathematical biology

12–19 **Assistant Professor**, *U. Michigan (Electrical Engineering and Computer Science)*, Ann Arbor.
Research, student supervision; robotics and control theory

11–12 **Visiting Assistant Professor**, *U. Michigan (Electrical Engineering and Computer Science)*.

09–12 **Postdoctoral Research Associate**, *U. Pennsylvania*, Philadelphia.
Research, student supervision; robotics and control theory
Advisors Mark Yim, Daniel E. Koditschek and George Pappas

06–09 **Graduate Student Researcher**, *U. California*, Berkeley.
Funded Ph.D. research; biomechanics

Tech Industry

19–now **General Manager**, *Izun, Inc.*, Ypsilanti.
Consulting

03–now **Founding partner**, *Bio-Signal Analysis*, Tel-Aviv.
Algorithms; Electrocardiology technology start-up

01–06 **Chief Architect, R&D**, *Harmonic, Inc.*, Sunnyvale.
R&D, embedded programming, algorithms; Company develops digital video equipment for cable and satellite

98–01 **Chief Architect**, *Harmonic Data, Ltd.*, Tel-Aviv.
Company-wide system architecture, basic research team manager, academic liaison; Company develops Internet over satellite solutions

96–98 **Instructor**, *John Bryce Training*, Ramat-Gan.
Teaching Java, Javascript, HTML; Company trains IT professionals

97 **Software Engineer**, *Compedia, Ltd*, Ramat-Gan.
Design and development of 3D video game engine; Company develops edutainment products for kids

Military Service (Israel)

96–17 **Reserve duty**, *IDF*.

93–96 **Mandatory service**, *IDF*.

Publications and Other Products

[1]S Revzen B Bittner R Hatton. "A Data-Driven Approach to Connection Modeling". In: *arXiv preprint* (2018). URL: [LINK].

[2]S Revzen B Bittner R Hatton. "Step Selection in Data-Driven Geometric Gait Optimization". In: *American Physical Society March Meeting*. 2018.

[3]B Banjanin, SA Burden, TY Moore, S Revzen, and RJ Full. "Estimating predictive dynamical models of legged locomotion from data". In: *Integrative and comparative biology*. Vol. 56. 2016, E11–E11.

[4]B A Bittner, R A Hatton, and S Revzen. "Geometrically Optimal Gaits: a Data-Driven Approach". In: *Nonlinear Dynamics* 94.3 (2018), pp. 1933–1948. DOI: 10.1007/s11071-018-4466-9.

[5]B Bittner, R L Hatton, and S Revzen. "Data-Driven Geometric System Identification for Shape-Underactuated Dissipative Systems". In: *arxiv* (2020). URL: [LINK].

[6]B Bittner and S Revzen. "Geometric Insights for Data-Driven Gait Analysis". In: *IEEE International Conference On Intelligent Robots and Systems, Workshop on Robotics Inspired Biology*. 2017. URL: [LINK].

[7]B Bittner and S Revzen. "The Locality of Data-Driven Models". In: *Dynamic Walking*. 2018.

[8]B Bittner and S Revzen. "What do nematode swimming gaits optimize?" In: *Yearly Meeting of the Society for Integrative and Comparative Biology*. 2018.

[9]B Bittner and S Revzen. "Optimizing Gaits for Coverage on Lie Groups". In: *Dynamic Walking*. Dynamic Walking. June 2019. URL: [LINK].

[10]B Bittner and S Revzen. "Optimizing Gaits for Coverage on Lie Groups". In: *Dynamic Walking*. 513. Dynamic Walking. Canmore AB, CA, June 2019. URL: [LINK].

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[13]S A Burden, S Revzen, and S S Sastry. "From anchors to templates: Exact and approximate reduction in models of legged locomotion". In: *Dynamic Walking*. 2013. URL: [LINK].

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